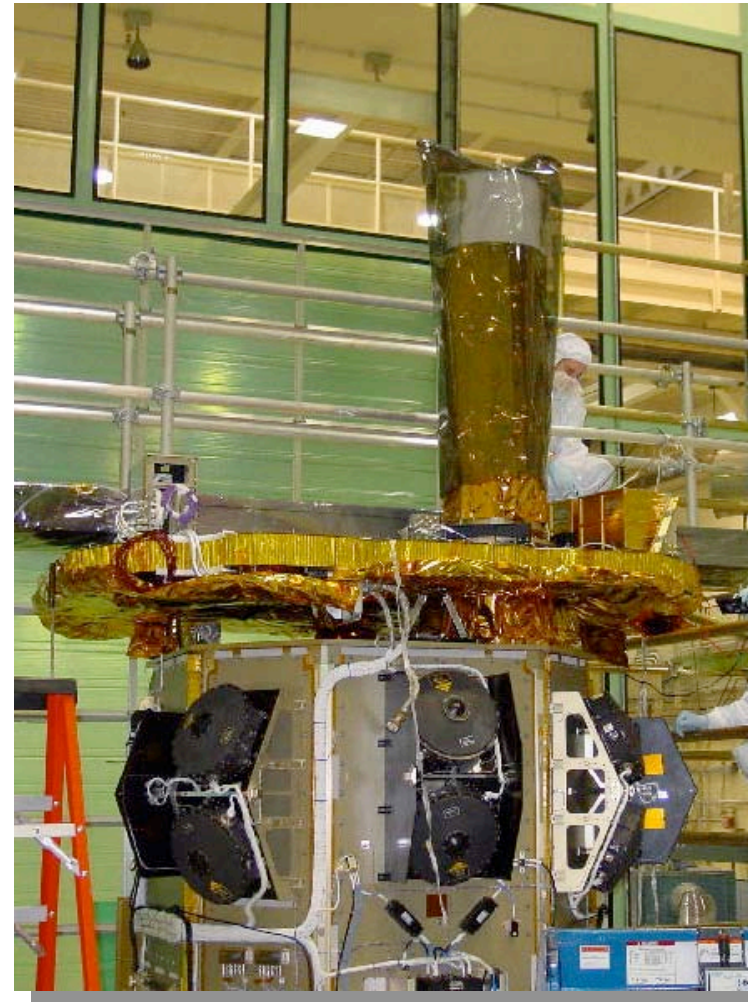
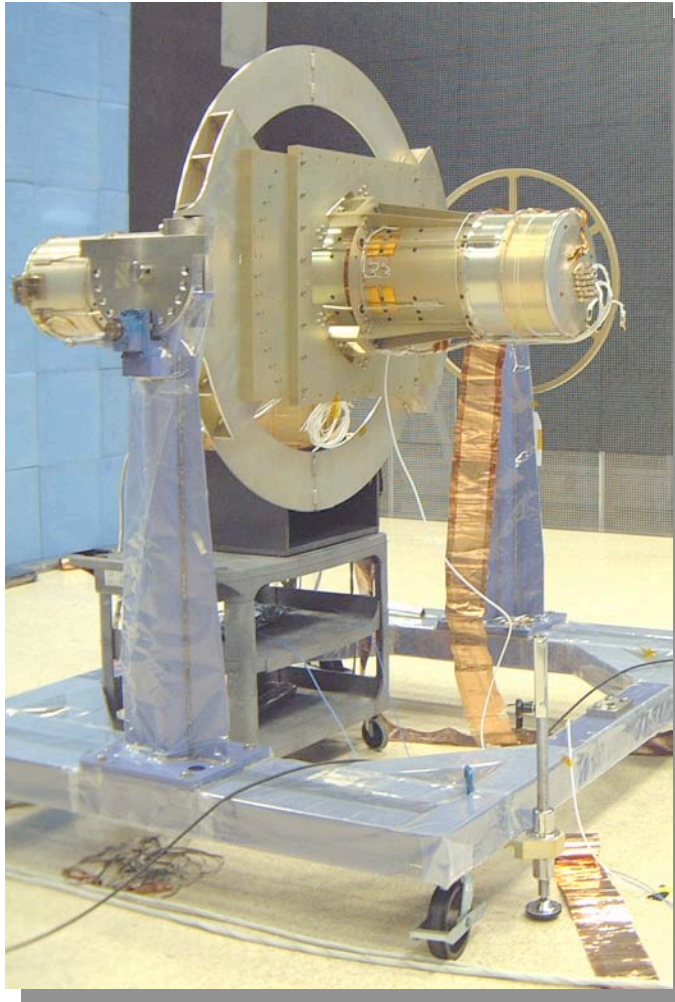


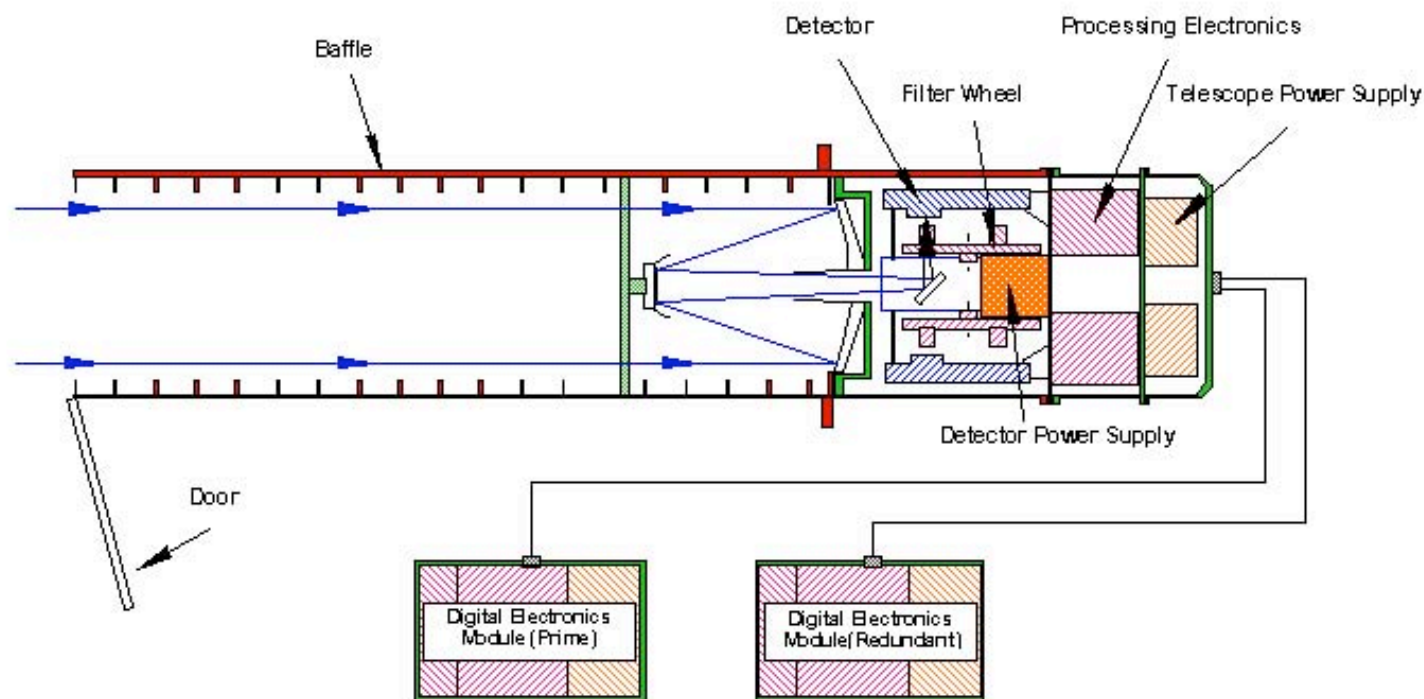


The Ultraviolet/Optical Telescope (UVOT)





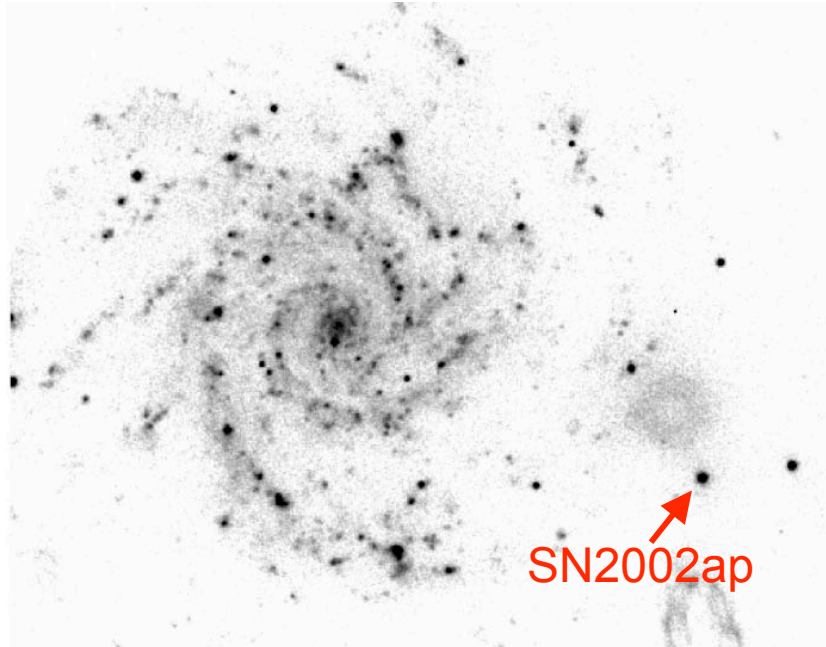
UVOT Schematic



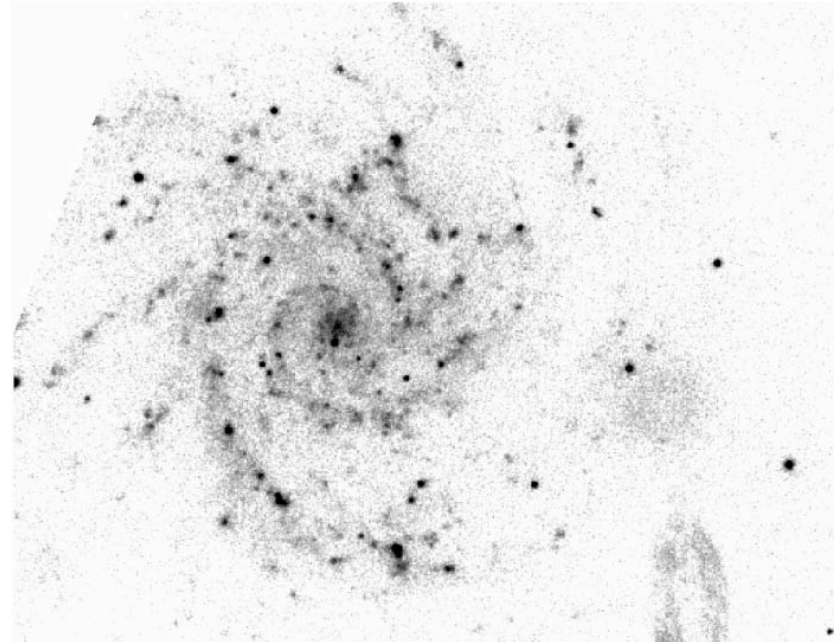


M74: XMM-OM

2002



2003



Images taken in 280nm filter



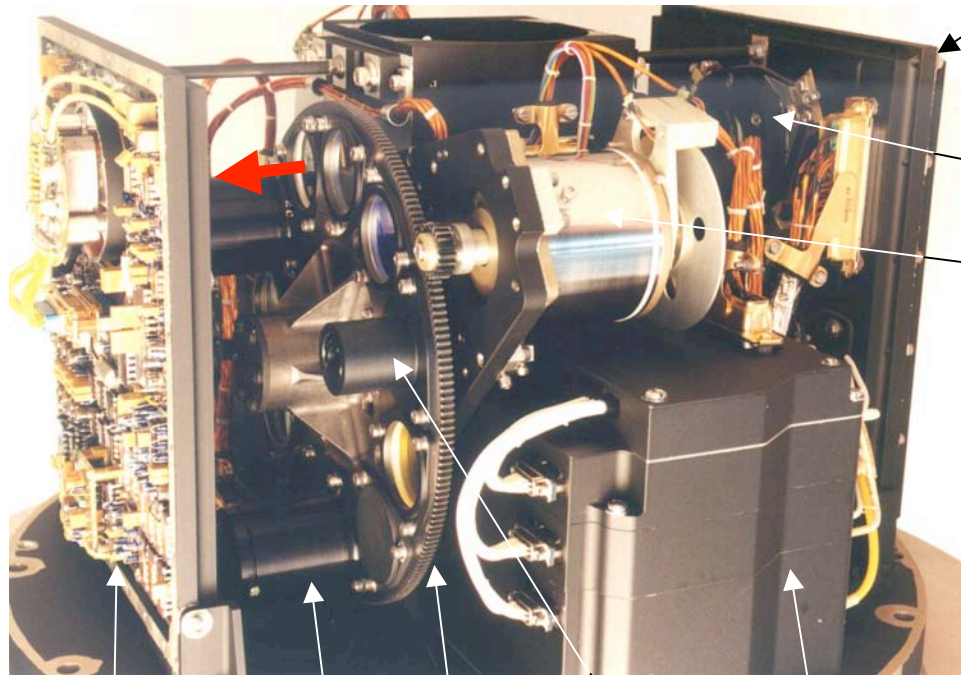
Swift community meeting
September 2004







UVOT detector module



prime detector camera unit

intensifier

filter wheel drive

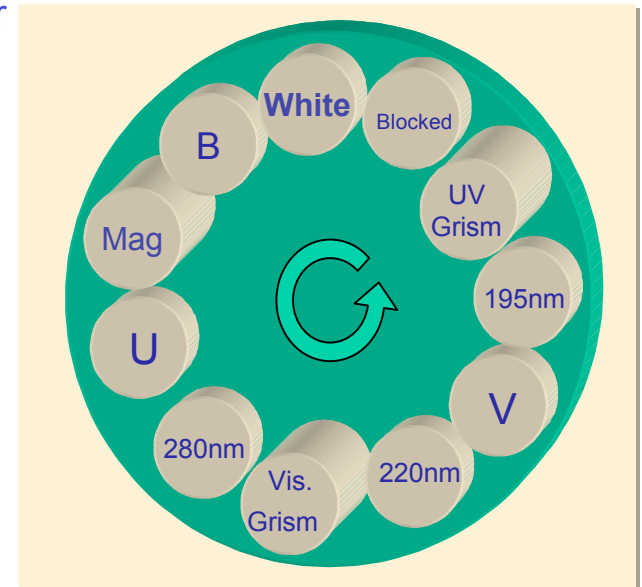
redundant detector camera unit with open back

grism

filter wheel loaded with optical elements

magnifier

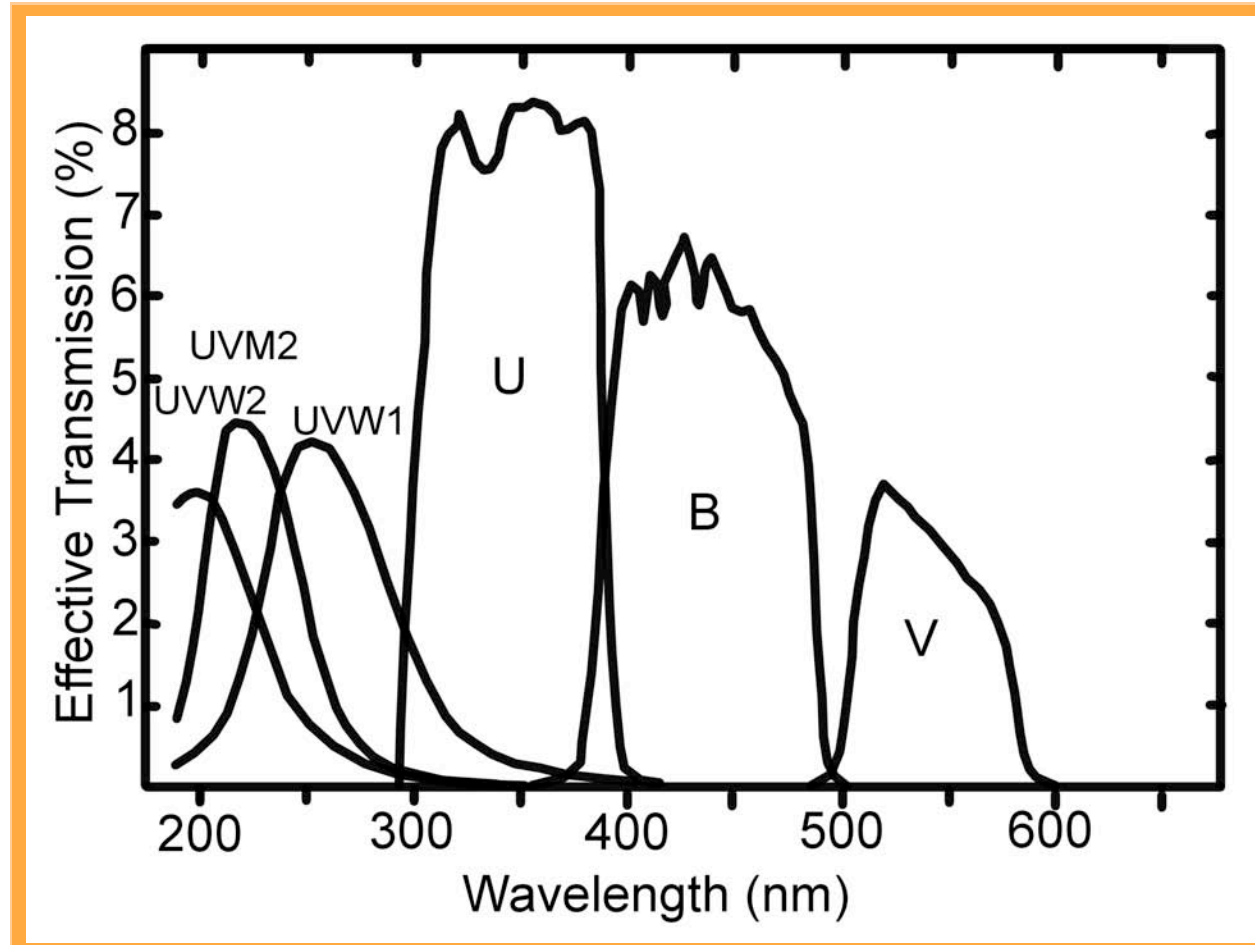
prime detector high voltage unit



Filter wheel schematic showing position of optical elements



Colour Filters





Limiting Magnitude

Expected performance				
	Spectral Type			
Filter	B0	A0	G0	K0
U	23.5	22.1	21.3	20.4
B	23.3	22.8	22.2	21.9
V	22.7	22.1	21.9	21.9
White	21.7	22.6	23.0	22.7

Limiting B magnitudes for a 5 sigma detection in 1000s



UVOT zero points

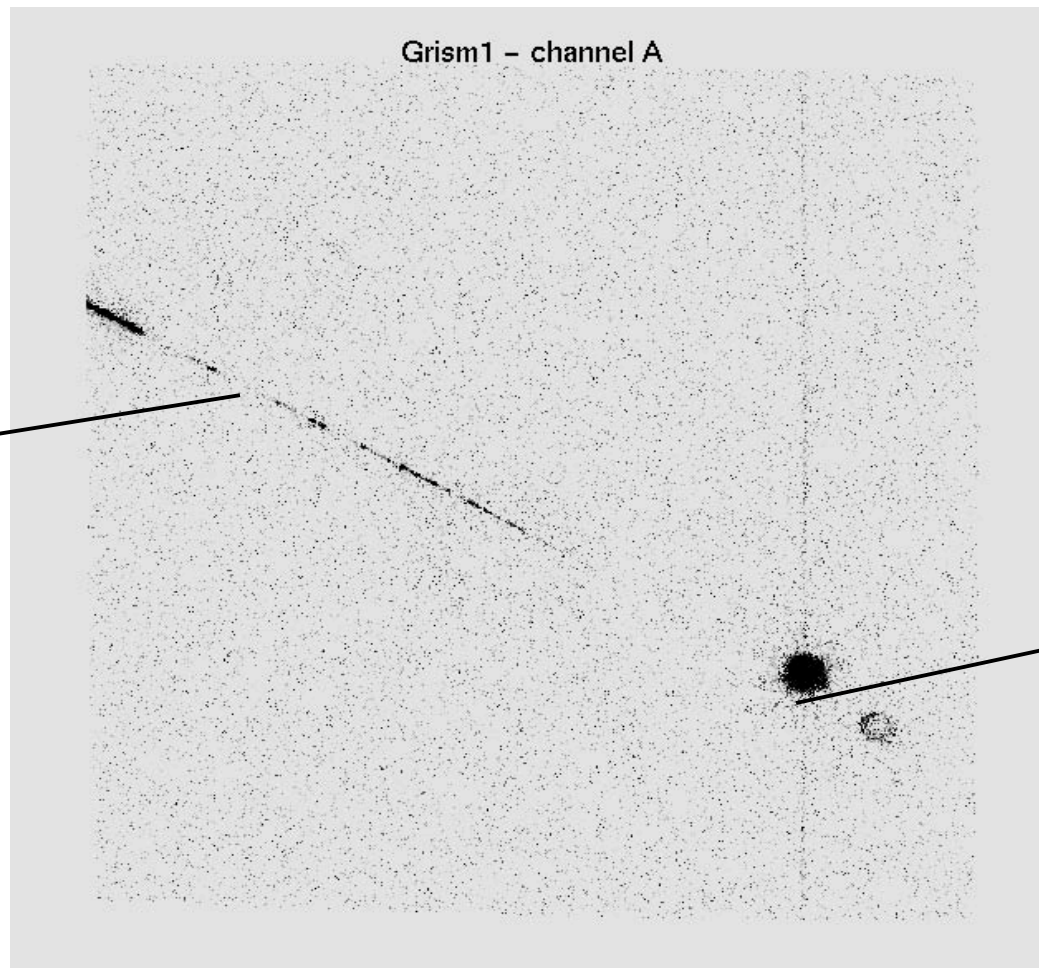
Estimated photometric zero points for an A0 star observed with the UVOT. The zero point corresponds to the stellar magnitude that yields 1 c/s in the detector.

Filter	$\lambda_{\text{cen}}(\text{nm})$	Chan A	Chan B
White		20.47	20.64
V	550	18.18	18.36
B	440	19.03	19.27
U	350	18.44	18.60
UVW1	260	17.82	17.99
UVM2	220	17.70	17.88
UVW2	200	17.77	17.89



Grism Data

Calibration
data



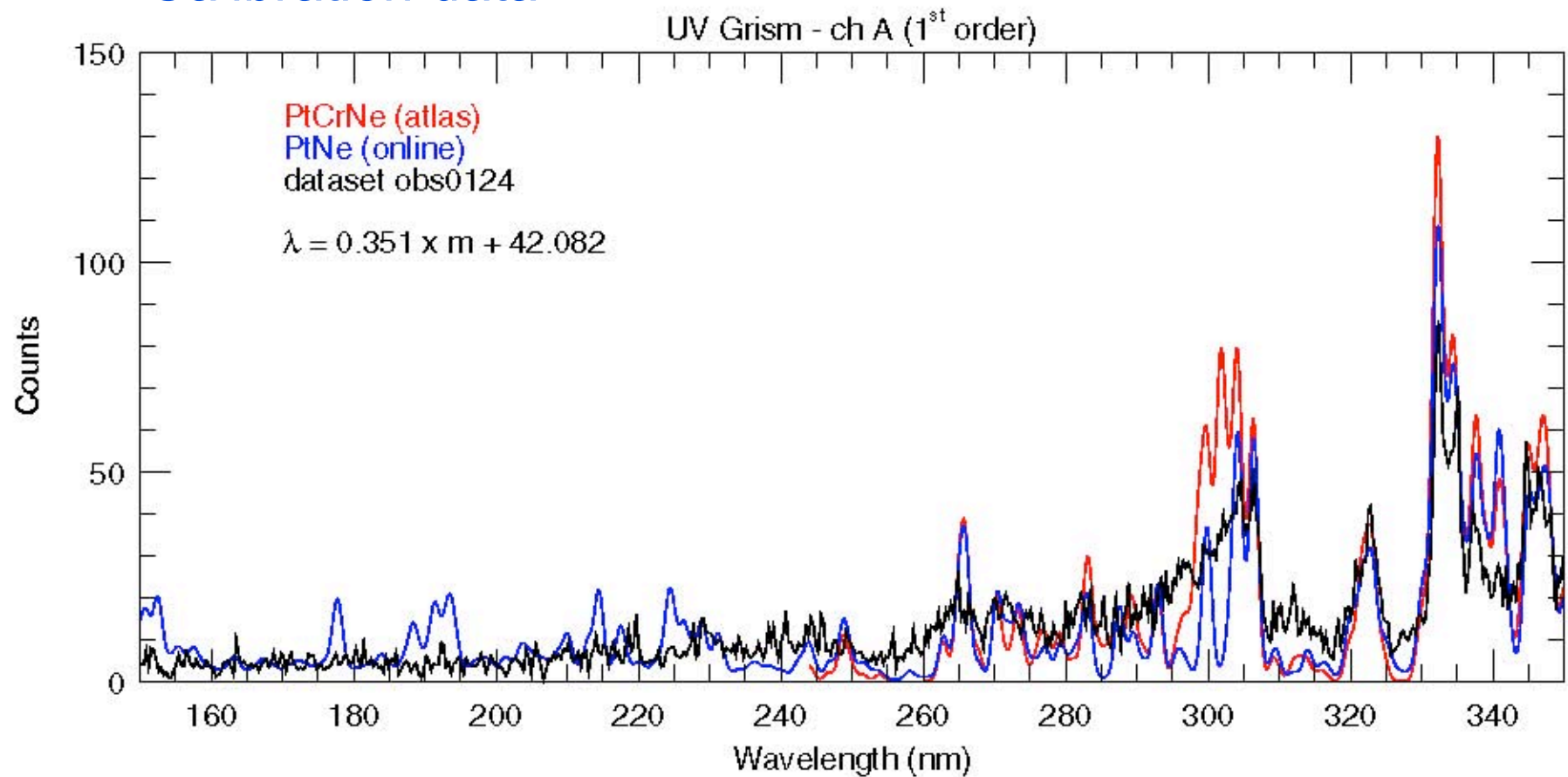
First order
dispersed
spectrum

Zero'th order



UV Grism

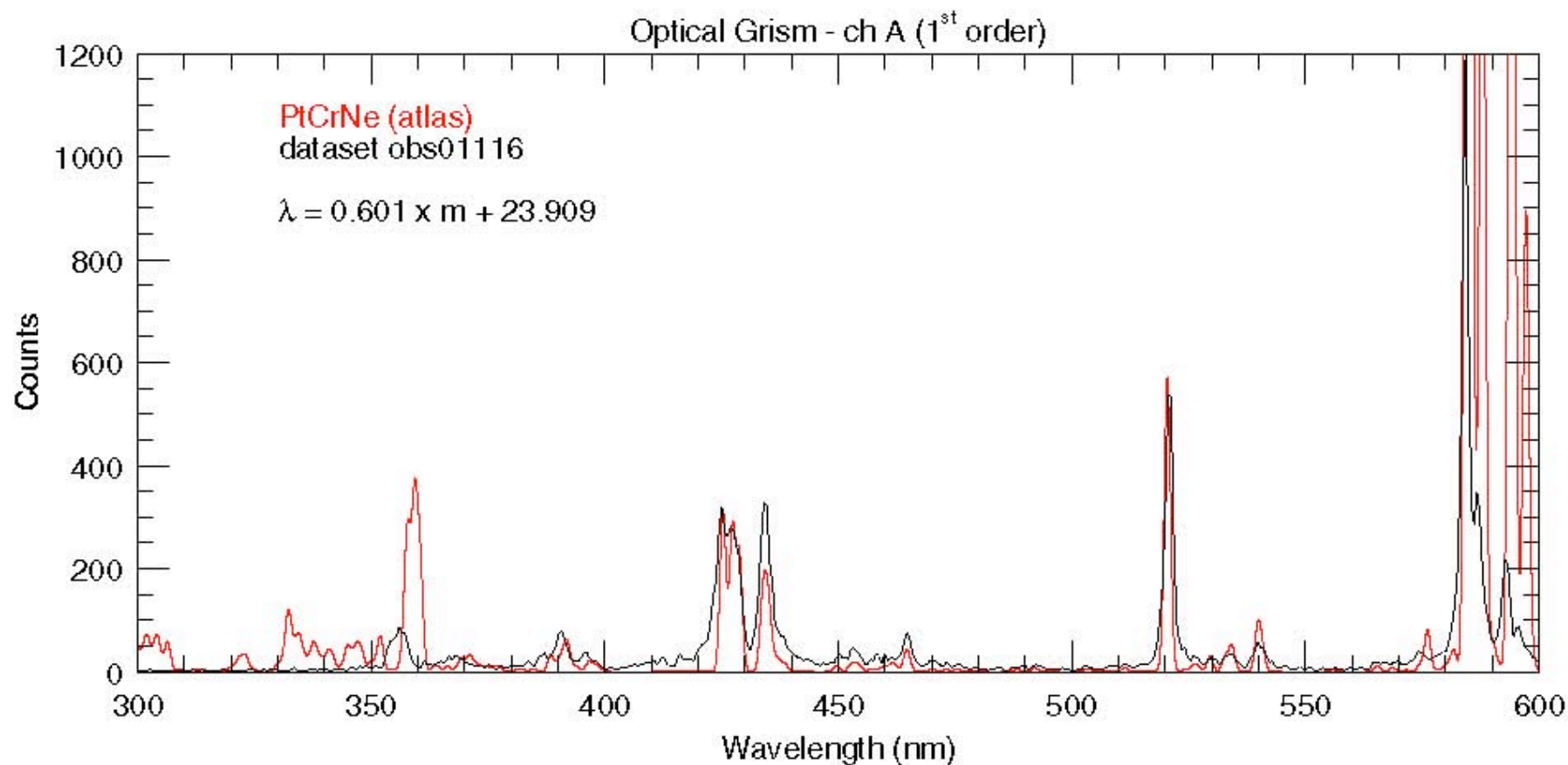
Calibration data





Optical Grism

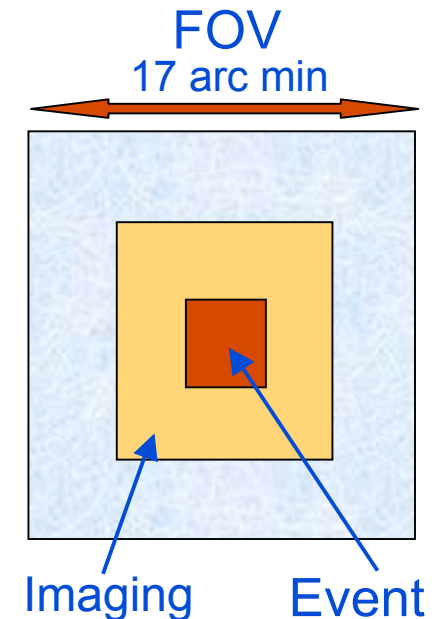
Calibration data





UVOT Observing modes

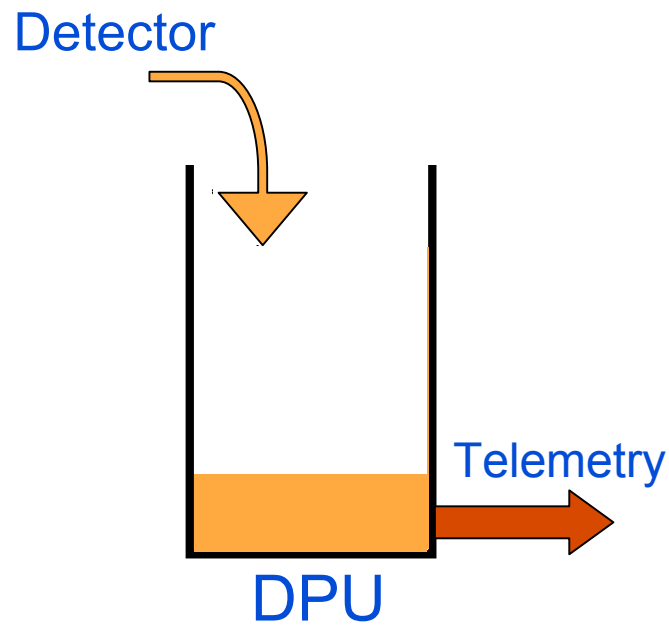
Mode	Description
Event	Record position and time of each photon event to ~11 ms accuracy
Imaging	Integrate image in onboard memory for preset exposure time, compensating for spacecraft motion



- Detector can be windowed in both modes
- Two modes can run simultaneously in different windows
- Choice of modes is a trade-off between science and available onboard memory
- Event mode used at beginning of automated burst response
 - Window size reduced as positional uncertainty improves
- Imaging mode used later in burst evolution when rate of change less.



Data flow





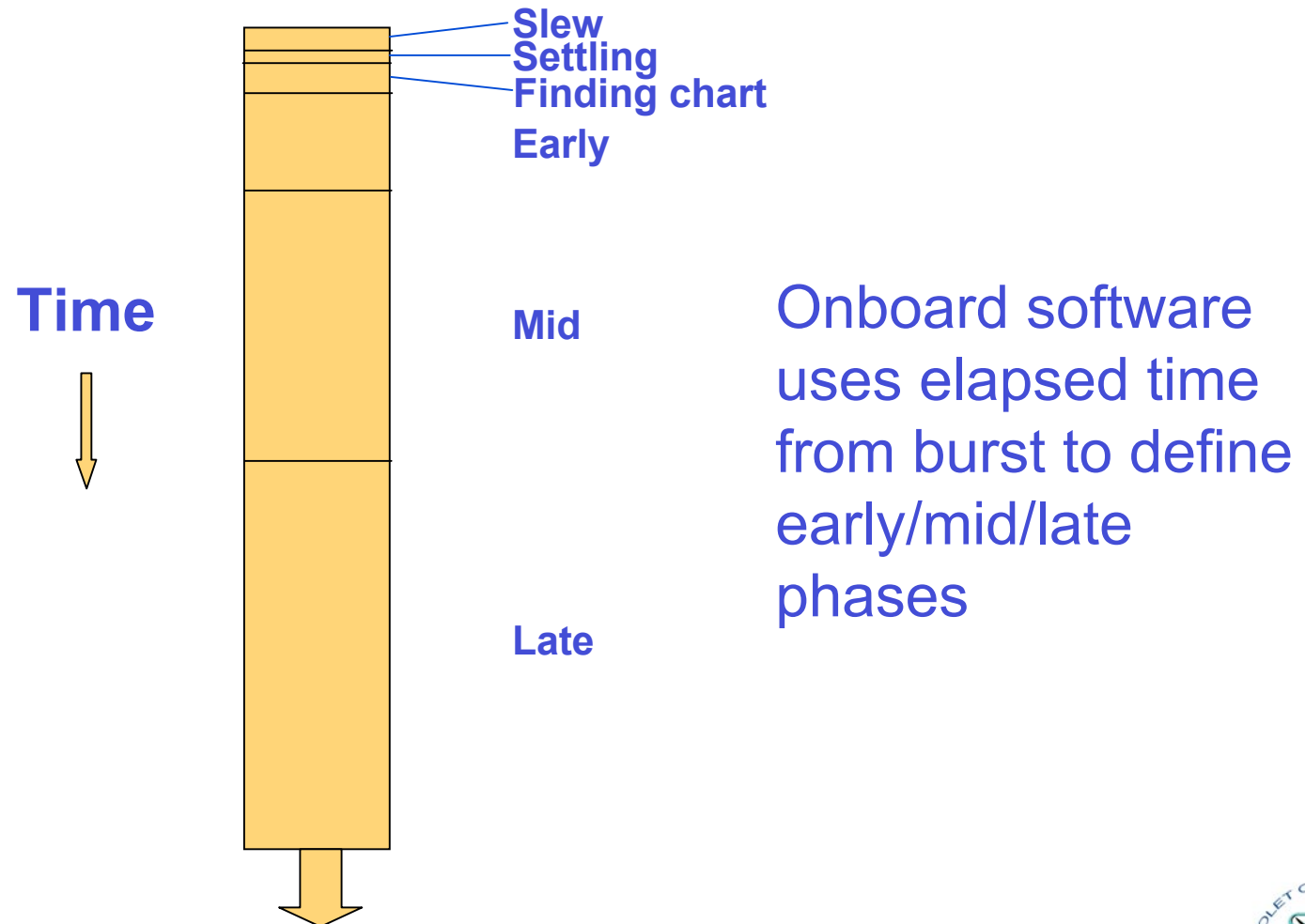
UVOT Automated Target (AT)

UVOT observing sequence for automated GRB response

- Multi-colour light curves by cycling filters
- Rapid cadence (exposures ~20 sec) at burst peak
 - Detector in event + image mode
- Exposures increased to 1000s as burst fades
 - Detector in image mode
- Choice of which filter elements are in sequence
 - A number of alternative sequences can be stored onboard



AT observation phases





Slewing

Slew



- S/C moving to target
 - Arrives in < 75 s
- UVOT HV not turned up
- No data are collected



< 75 s



Settling

Slew



< 75 s

Settle

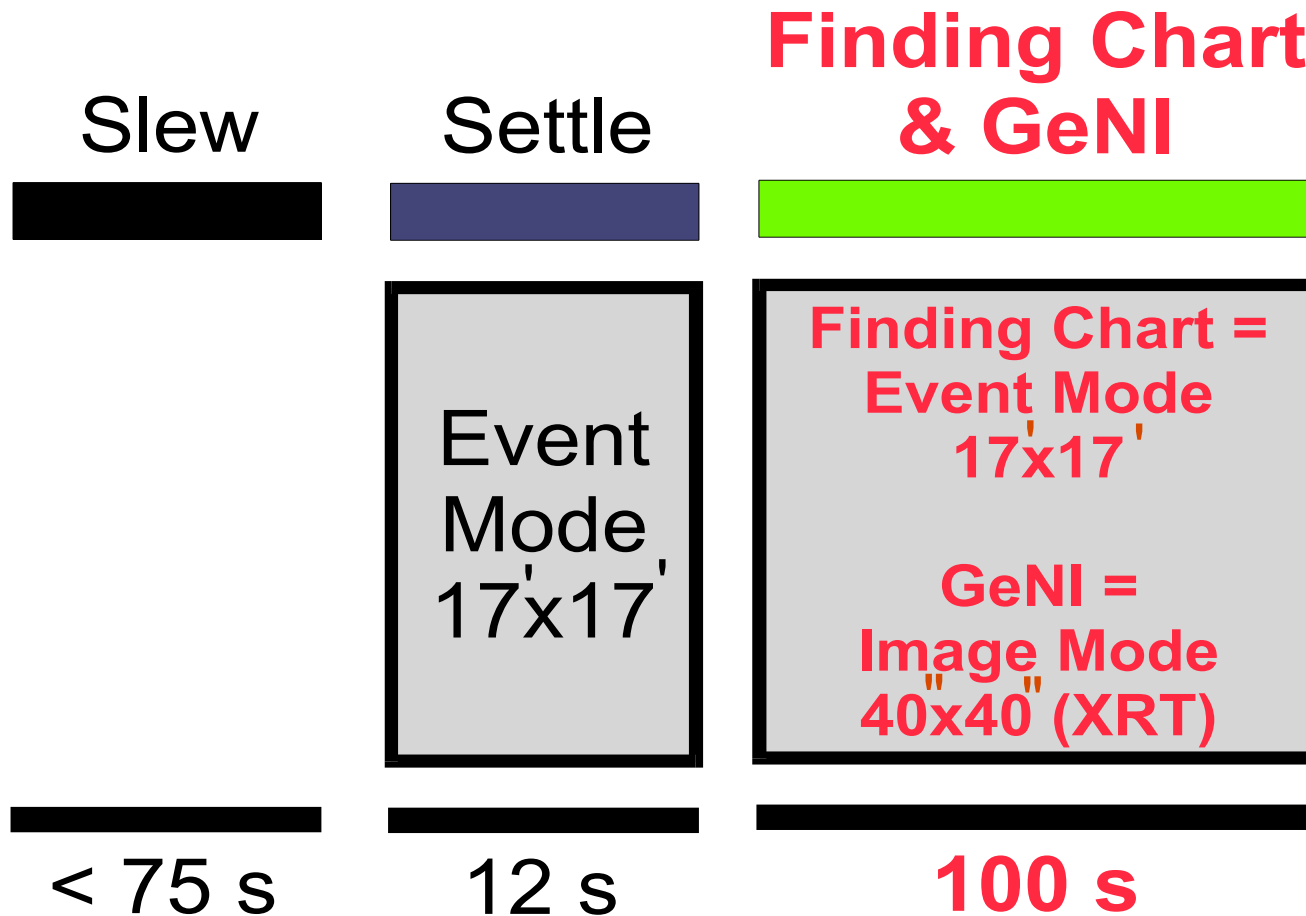


12 s

- S/C settling on target
 - Approximately 12 s
- Target moving in UVOT FoV
- Mode = Event
- FoV = Full
- Filter = UVW2 (200nm)
- Exposure = ~12 s
- Data sent thru Malindi



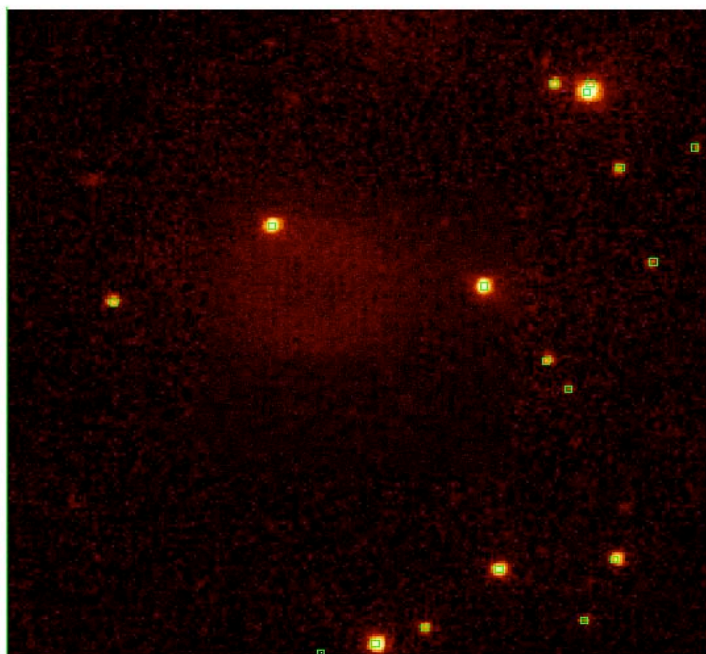
Finding Chart & GeNI





Finding Chart (Cont)

UVOT Image



Finding Chart
(Bright Pixel List)



This OM image was sent through the FC during SVP. Green boxes mark the 5x5 postage stamps that are telemetered.



Finding Chart

- S/C tracking target
- Finding Chart
 - Mode = Event
 - FoV = Full
 - Filter = V
 - Exposure = 100 s
 - Parameterized data sent thru TDRSS to GCN
 - Entire Finding Chart data sent thru Malindi



GRB Neighborhood Image (GeNI)

- GeNI
 - Mode = Image
 - FoV = 40x40 arcsec (Centered on XRT position)
 - FoV = 320x320 arcsec (Centered on BAT position)
 - Filter = V
 - Exposure = 100 s
 - Binning = 1x1 (w/ XRT position)
 - Binning = 8x8 (w/ Bat position)
 - Data sent thru TDRSS to GCN



AT - Early Time

Finding Chart
& GeNI



100 s

Early Time

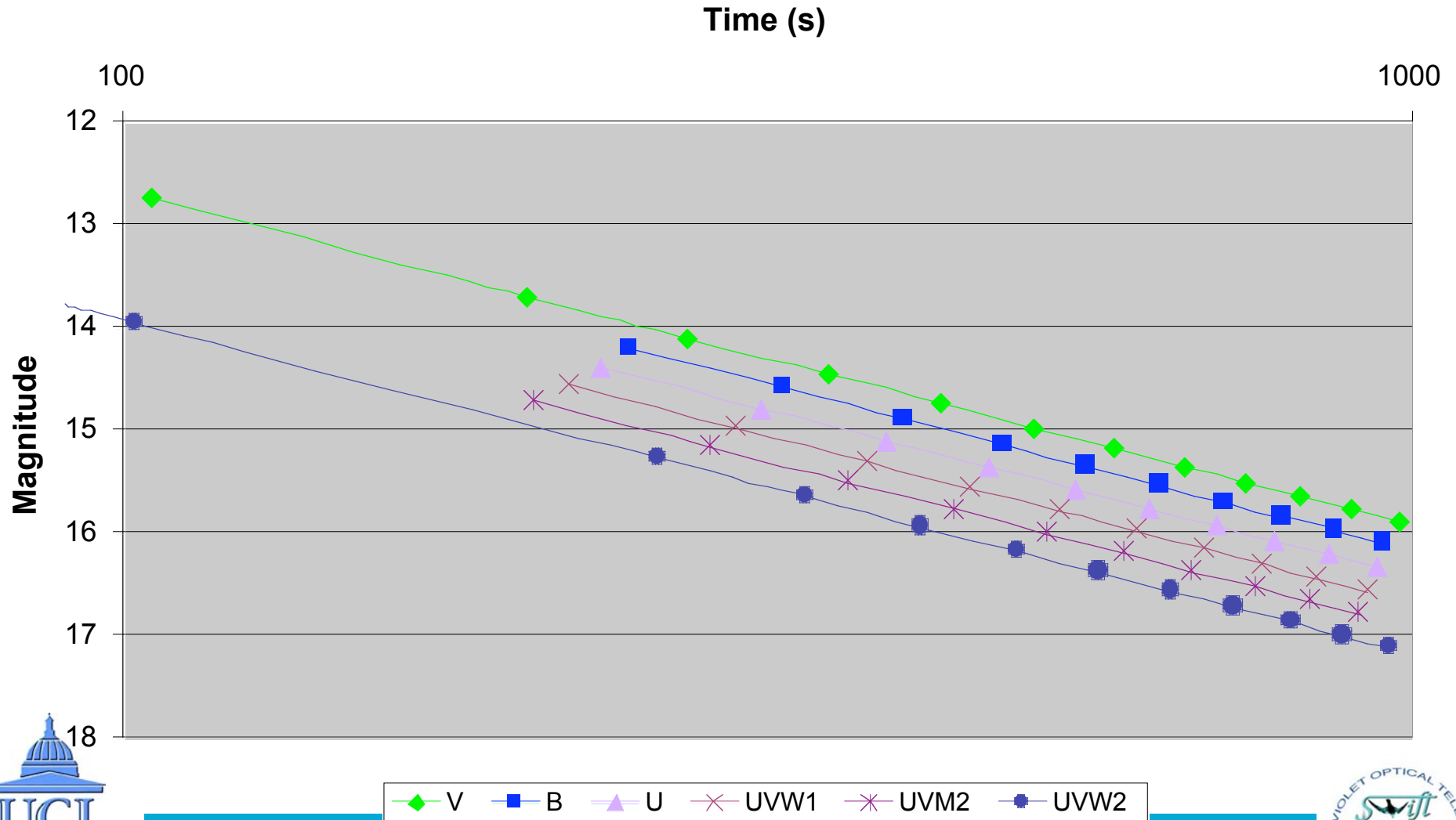


780 s

- Mode = Event
- FOV = 12x12 arcmin
- Filters = Broadband
- Exposure = 20 s
- Data sent thru Malindi



AT - Light Curve (Early)





AT (Middle Time)

Early Time



780 s

Mid Time

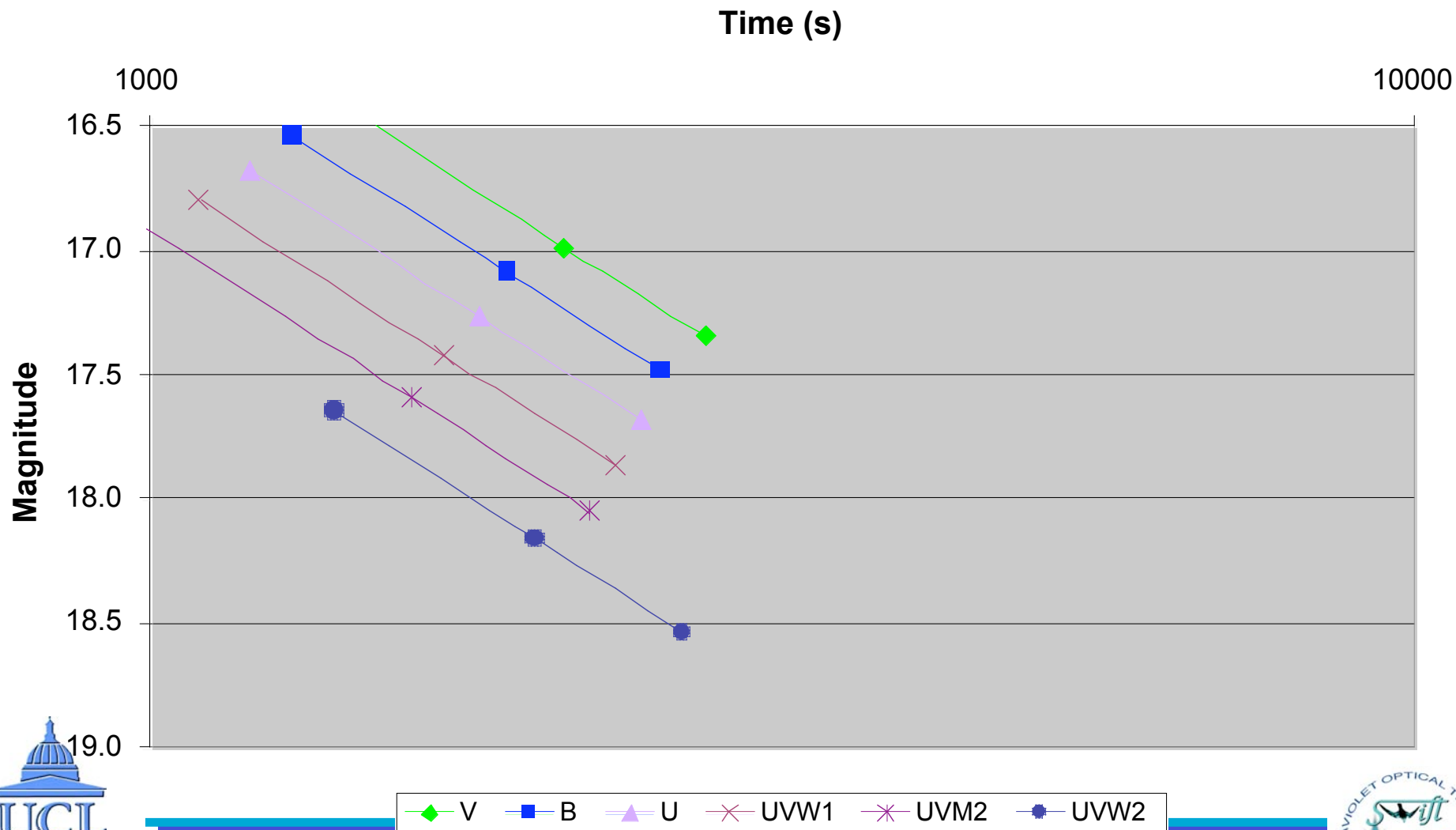


3100 s

- Mode = Event & Image
- FOV = 8'x8' (Event) & 12'x12' (Image)
- Filters = Broadband
- Exposure = 100 s
- Binning = 2x2
- Data sent thru Malindi



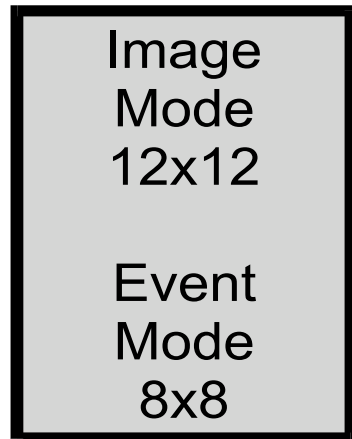
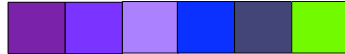
AT – Light Curve (Middle)





AT (Later Time)

Mid Time



3100 s

Later
Time

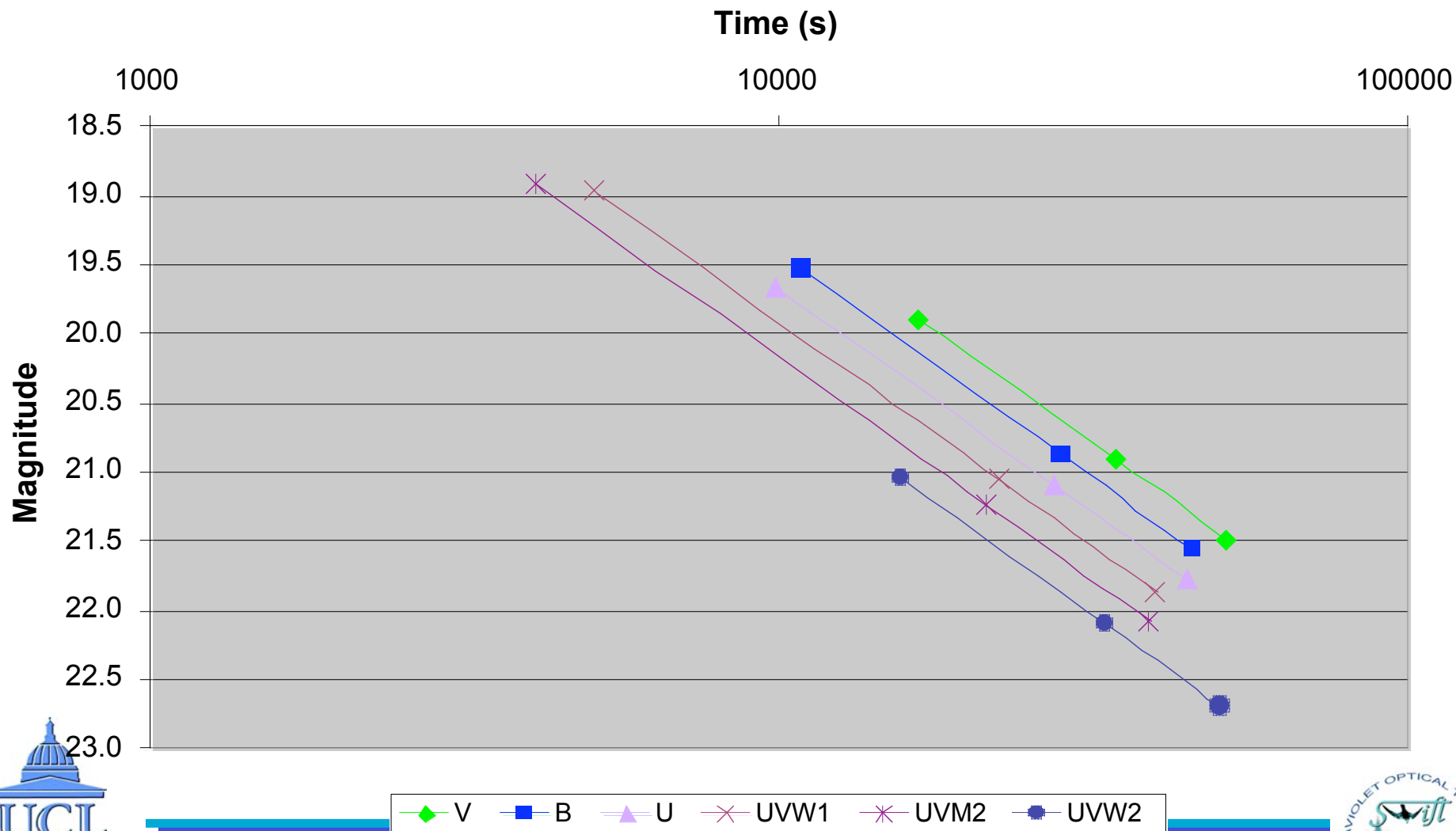


10000+ s

- Mode = Image
- FOV = 12'x12'
- Filters =
Broadband
- Exposure = 900 s
- Binning = 2x2
- Data sent thru
Malindi

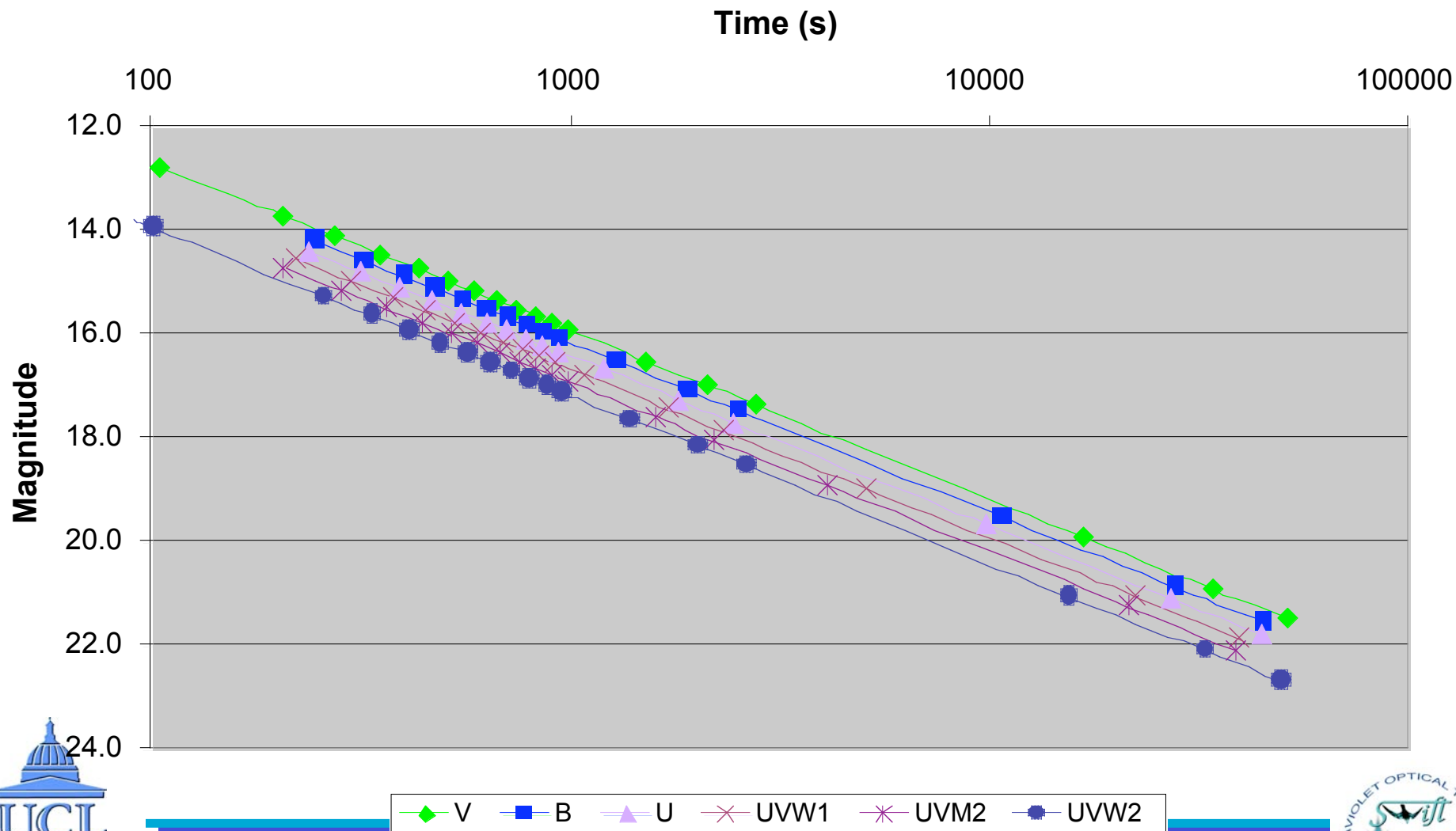


AT – Light Curve (Later)

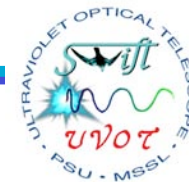




AT –Light Curve (Total)



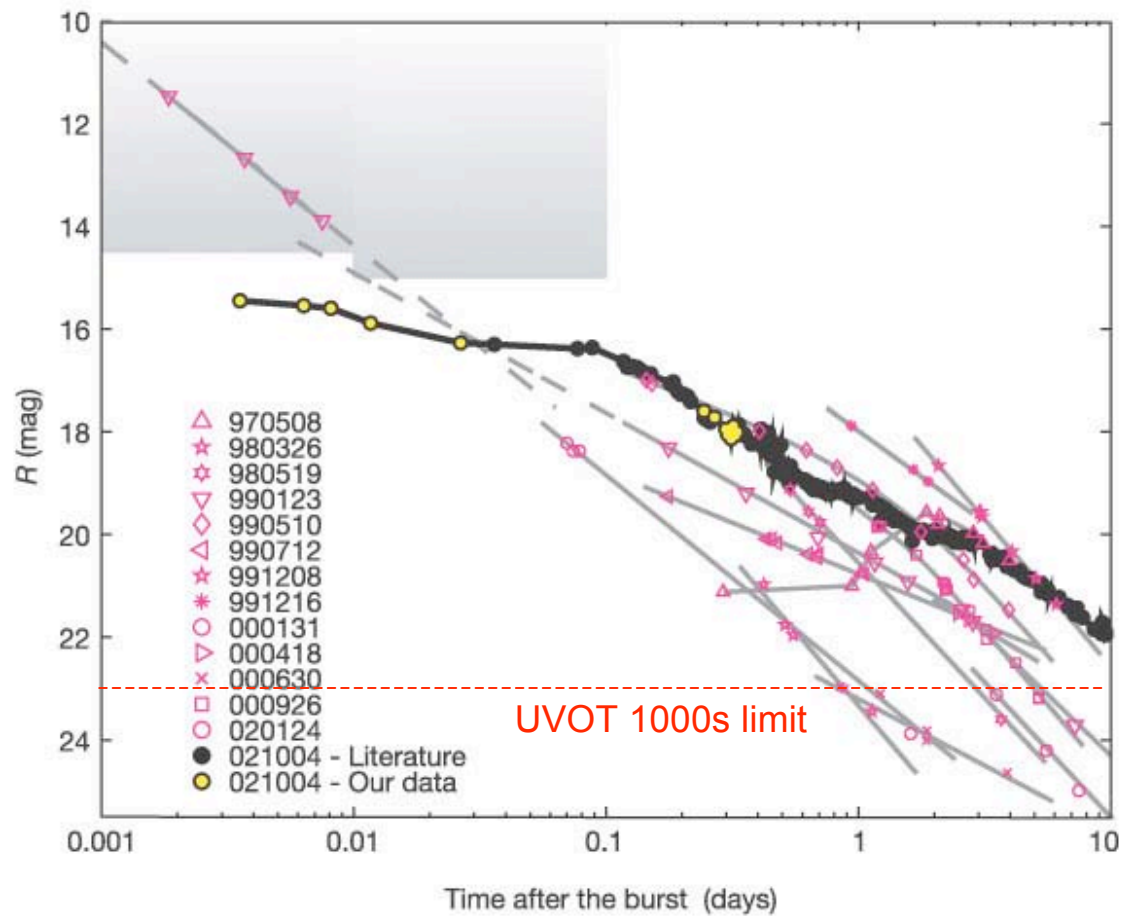
Swift community meeting
September 2004





In context...

Fox et al. 2003
Nature 422, 284



End

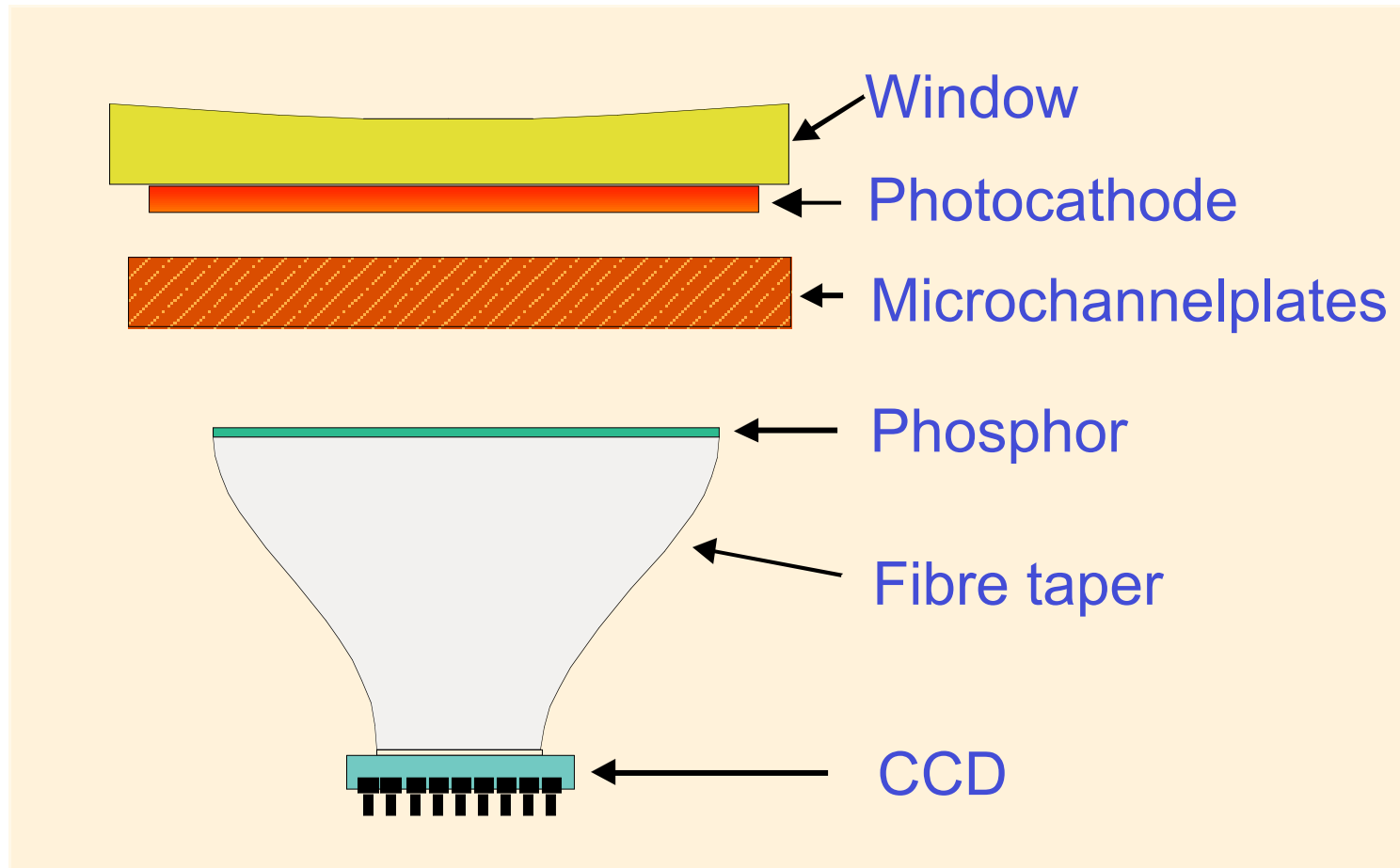


Instrument Characteristics

BAT	XRT	UVOT
<ul style="list-style-type: none"> •Wide FoV coded-aperture imager •Detectors: CdZnTe •Detection elements: 256 x 128 •FOV: 1.4 steradians •Spatial resolution: 20 arcmin •Energy range: 15-150 keV •Eff. Area: 5200 cm² •Energy Res: 3.3 keV at 60 keV •Astrometry: 4 arcmin •Sensitivity: 5x better than BATSE 	<ul style="list-style-type: none"> •Wolter 1 X-ray telescope •CCD camera: 600x600 pixels •FOV: 24x24 arcmin •Pixel: 2.4 arcsec •Energy range: 0.2-10 keV •Eff. Area: 110 cm² (1.5 keV) •Energy Res: 130 eV •Astrometry: <2.5 arcsec •Sensitivity: 2x10⁻¹⁴ erg/cm²/s 	<ul style="list-style-type: none"> •Modified Ritchey-Chretien telescope •Intensified CCD: 2048x2048 pixels •FOV: 17x17 arcmin •Pixel: 0.5 arcsec •Wavelength range: 170-650 nm •Eff. Area: 90 cm² (250 nm) •Wavelength discrimination: colour filters, Grisms ($\lambda/\Delta\lambda \sim 300$) •Astrometry: <0.3 arcsec •Sensitivity: B=24 (unfiltered)

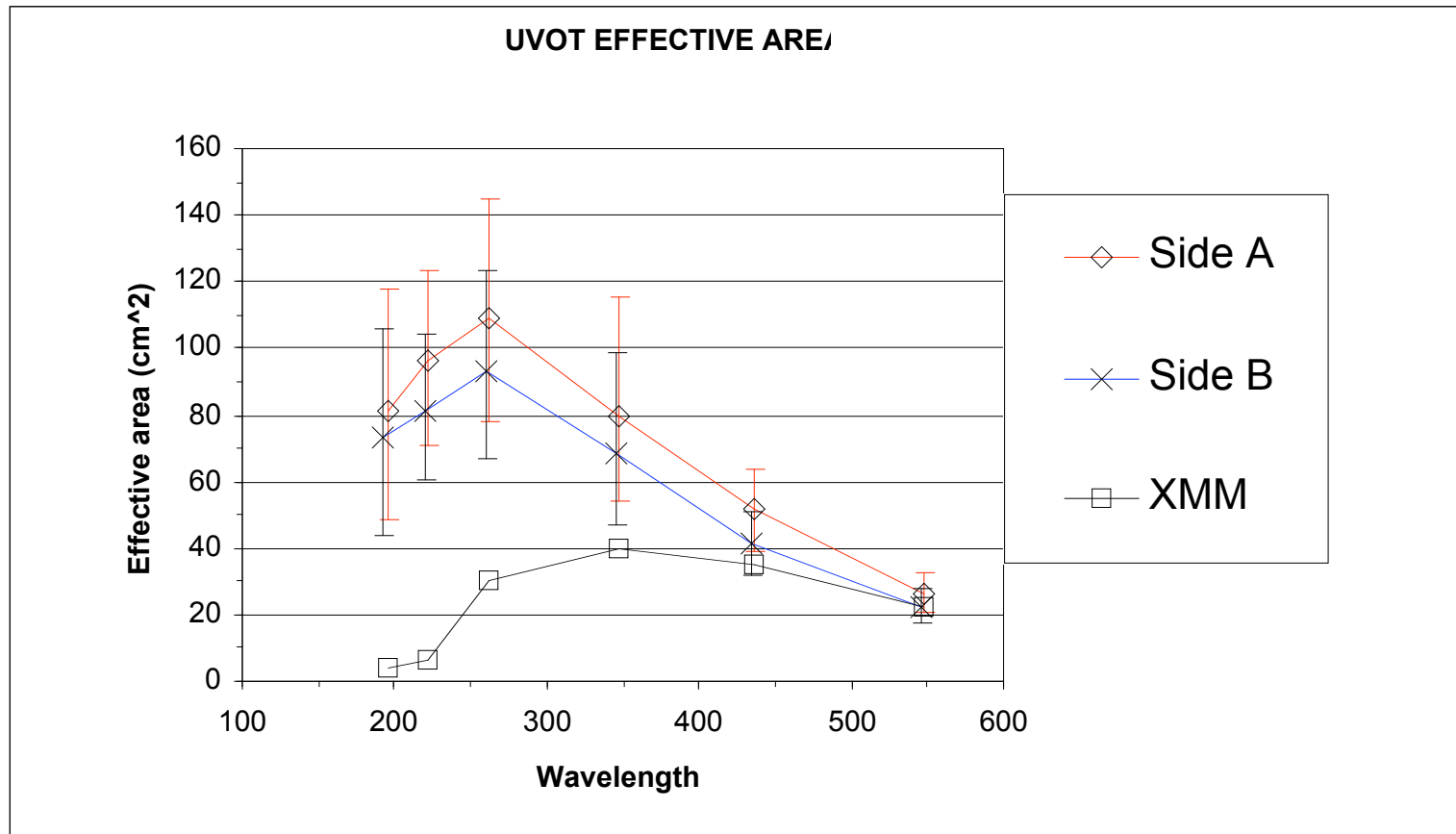


MIC Detector Schematic





Range & Responsivity



'White light' filter response